

# **Projections Perspective Math And Programming**

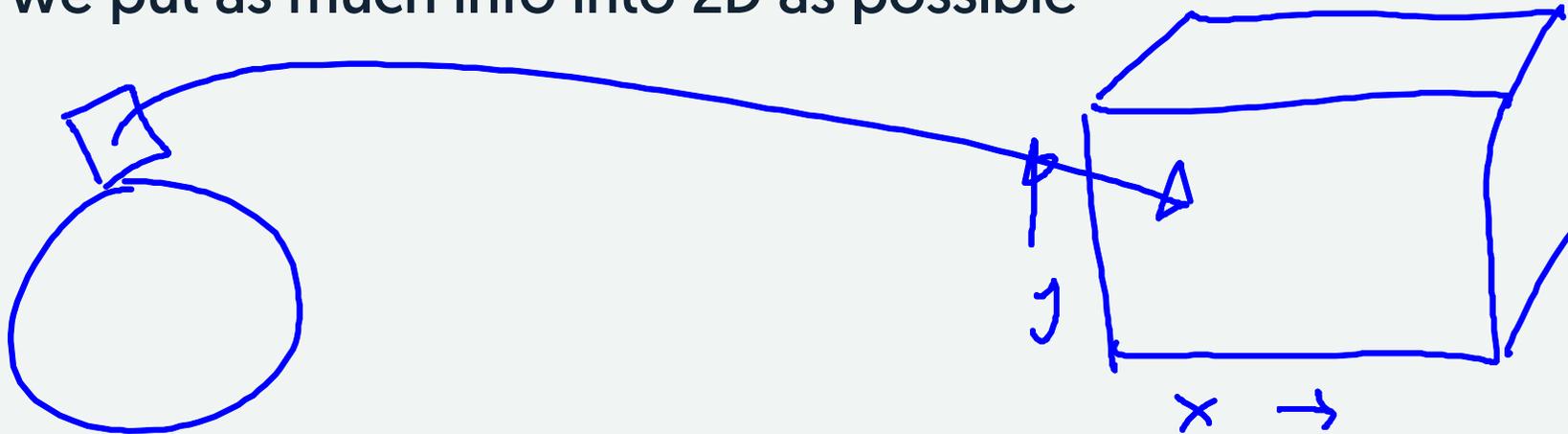
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# Projection 3D to 2D

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We lose a dimension

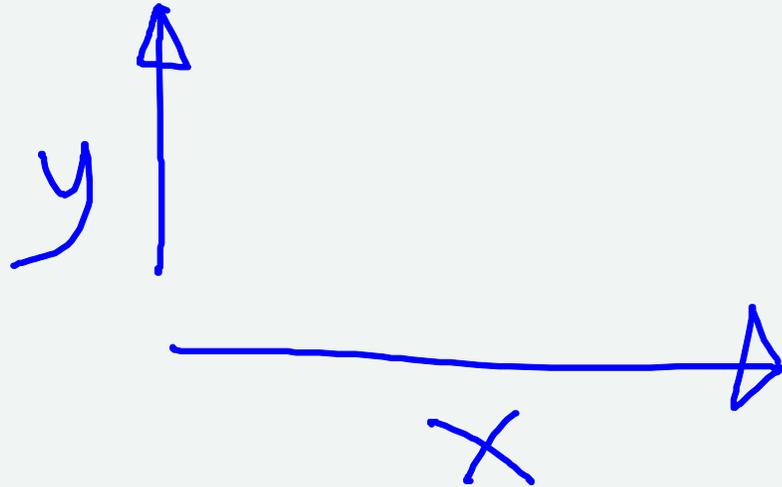
- No - we actually keep it (screen as a fishtank)
- Yes - we put as much info into 2D as possible



# The Screen as a Fishtank

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- X and Y (front/back)
- Z into screen
  - negative Z into screen



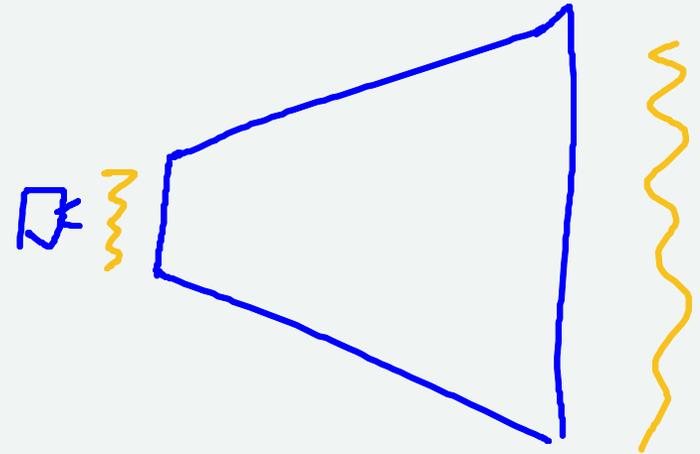
# Near and Far

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Some things are too close (in front of fishtank)

Some things are too far (behind fishtank)

Need to limit things for technical reasons



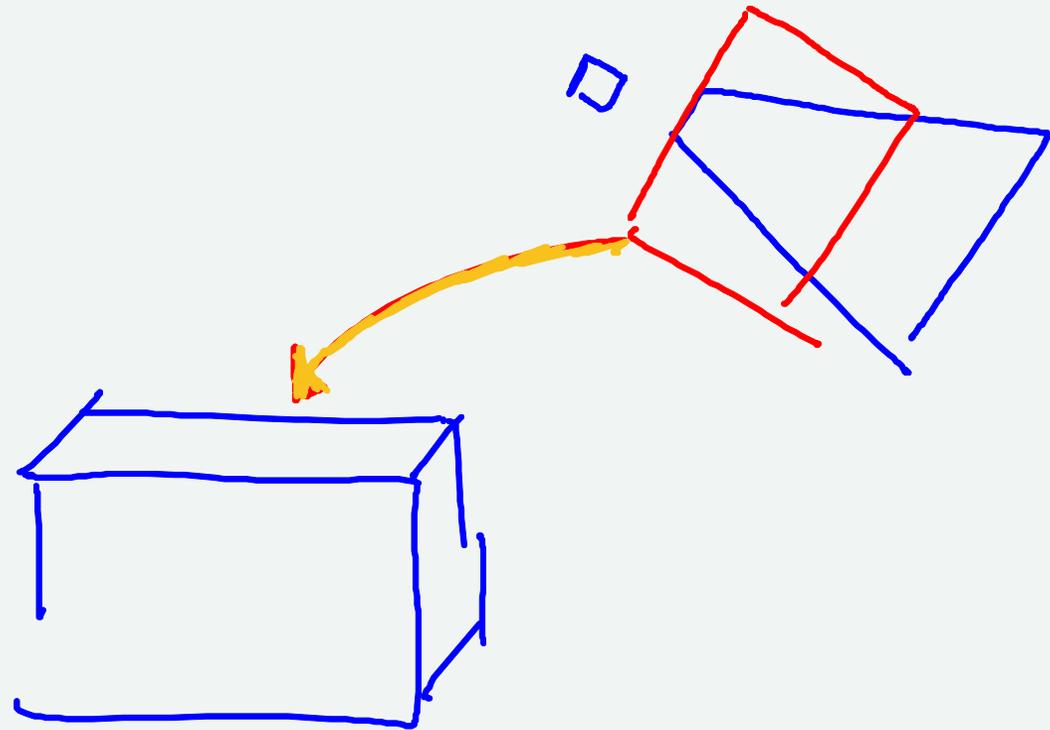
# Projection

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From: What is in front of camera

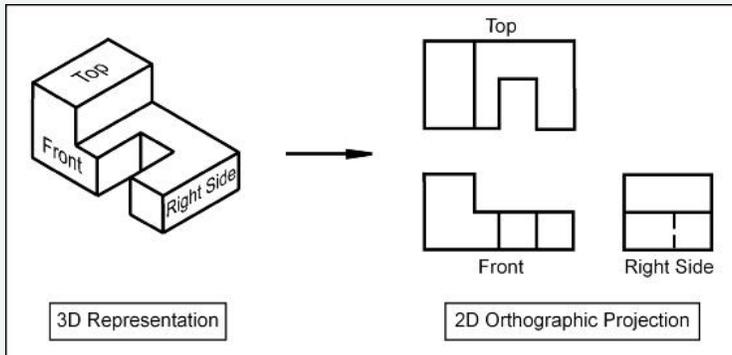
To: Screen Fishtank

It's a **transformation**



# Types of Projections

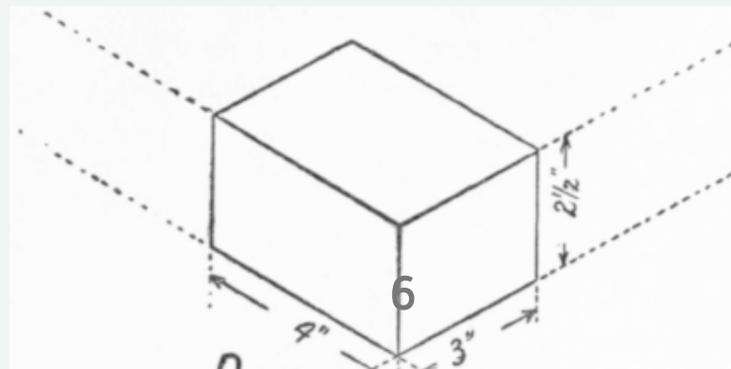
## Orthographic



## Isometric

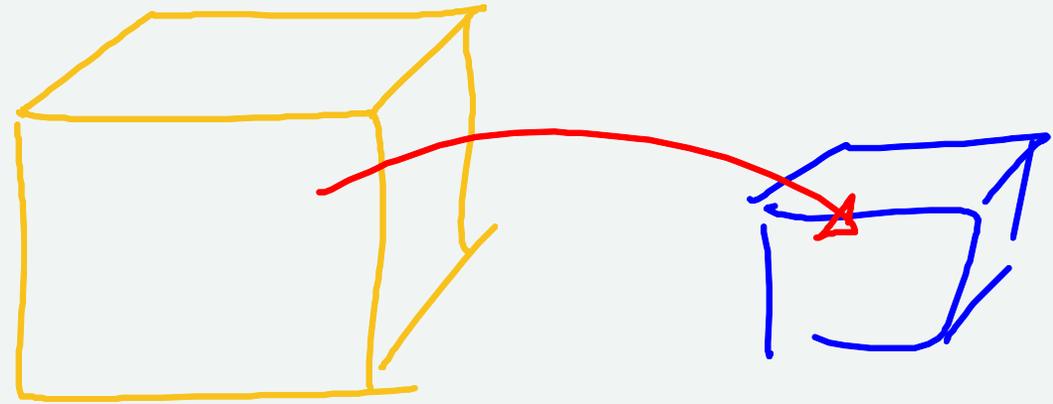


## Perspective



# Orthographic

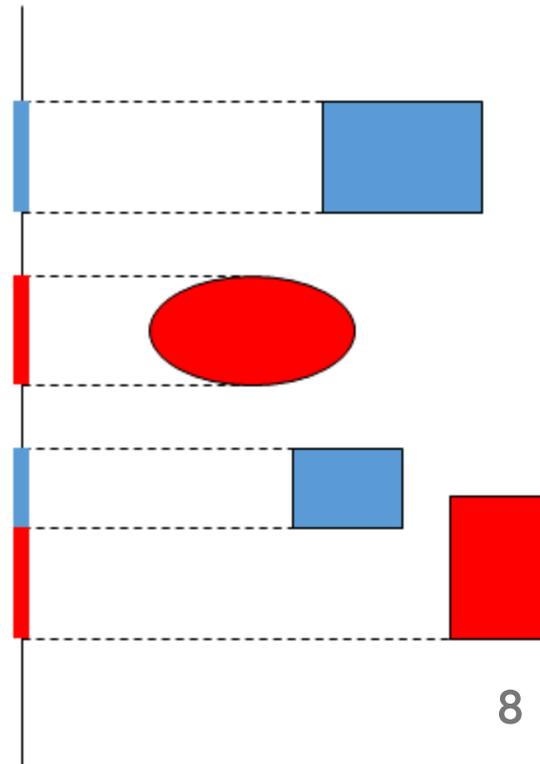
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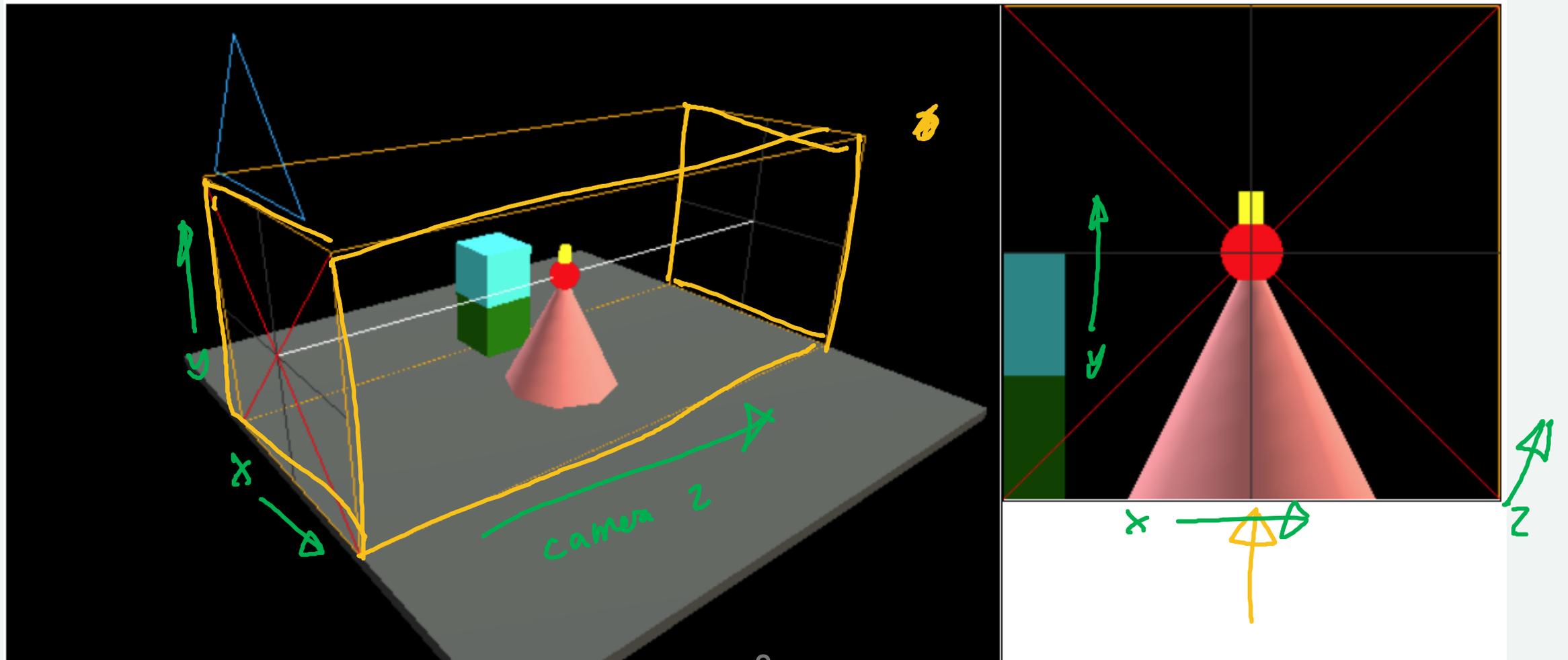
# Orthographic Projection

Projection = transformation that reduces dimension

Orthographic = flatten the world onto the film plane



# The Orthographic "Box"

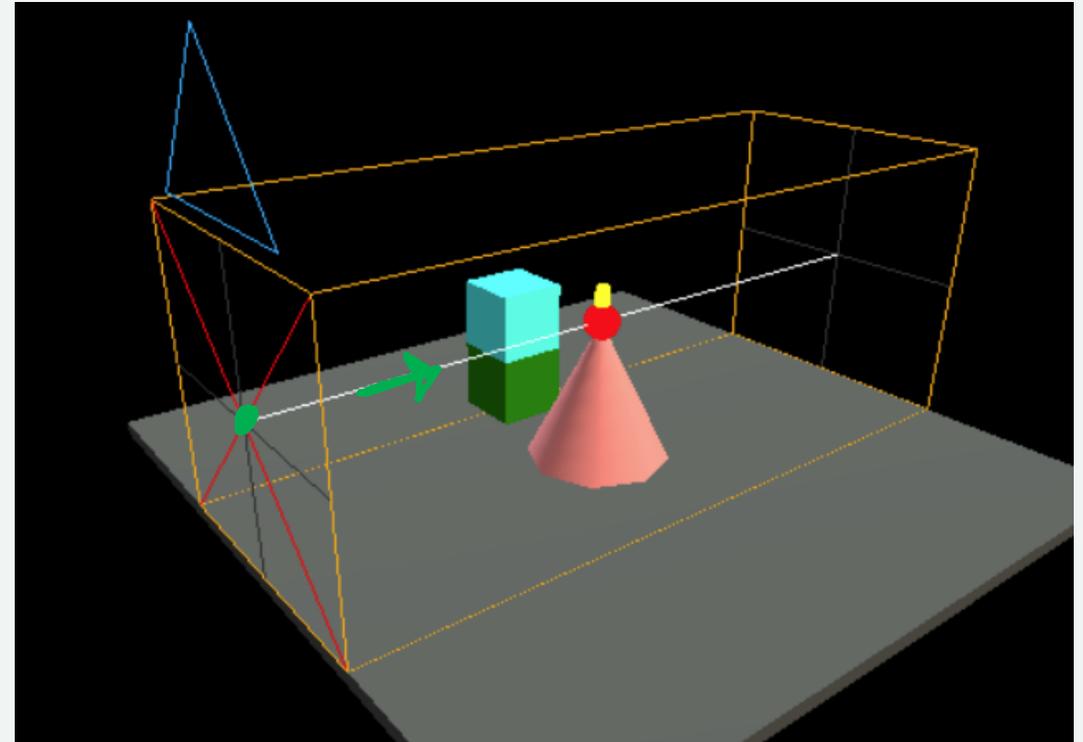


# The Orthographic "Box"

It is a "Camera Object"

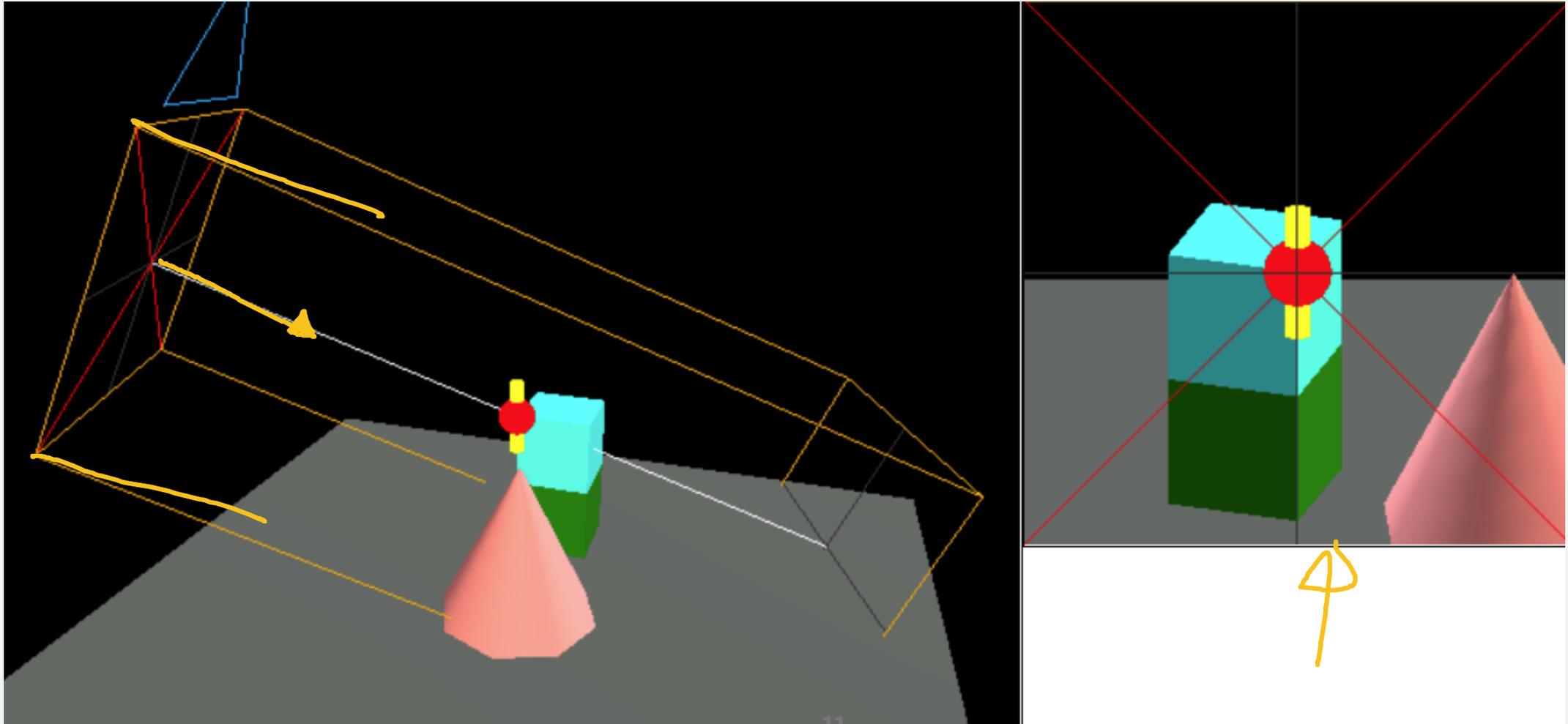
It is a Box in the World

- position (eye point)
- forward direction (neg Z)
- up direction (Y)
- size (left/right/top/bottom)
- front/back



Box maps to "screen box"

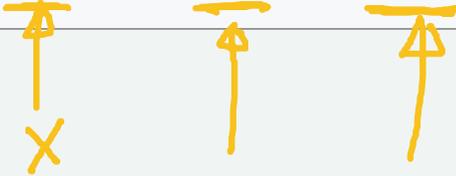
# You can orient the Box (rotate)



# Orthographic

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```
new T.OrthographicCamera(-2,2, -2,2, -2,2);
```



The screen (x,y,z)

Shift and scale to fit

Rotations to get top, side, front

Scales the "box" to the "screen box"

# Perspective

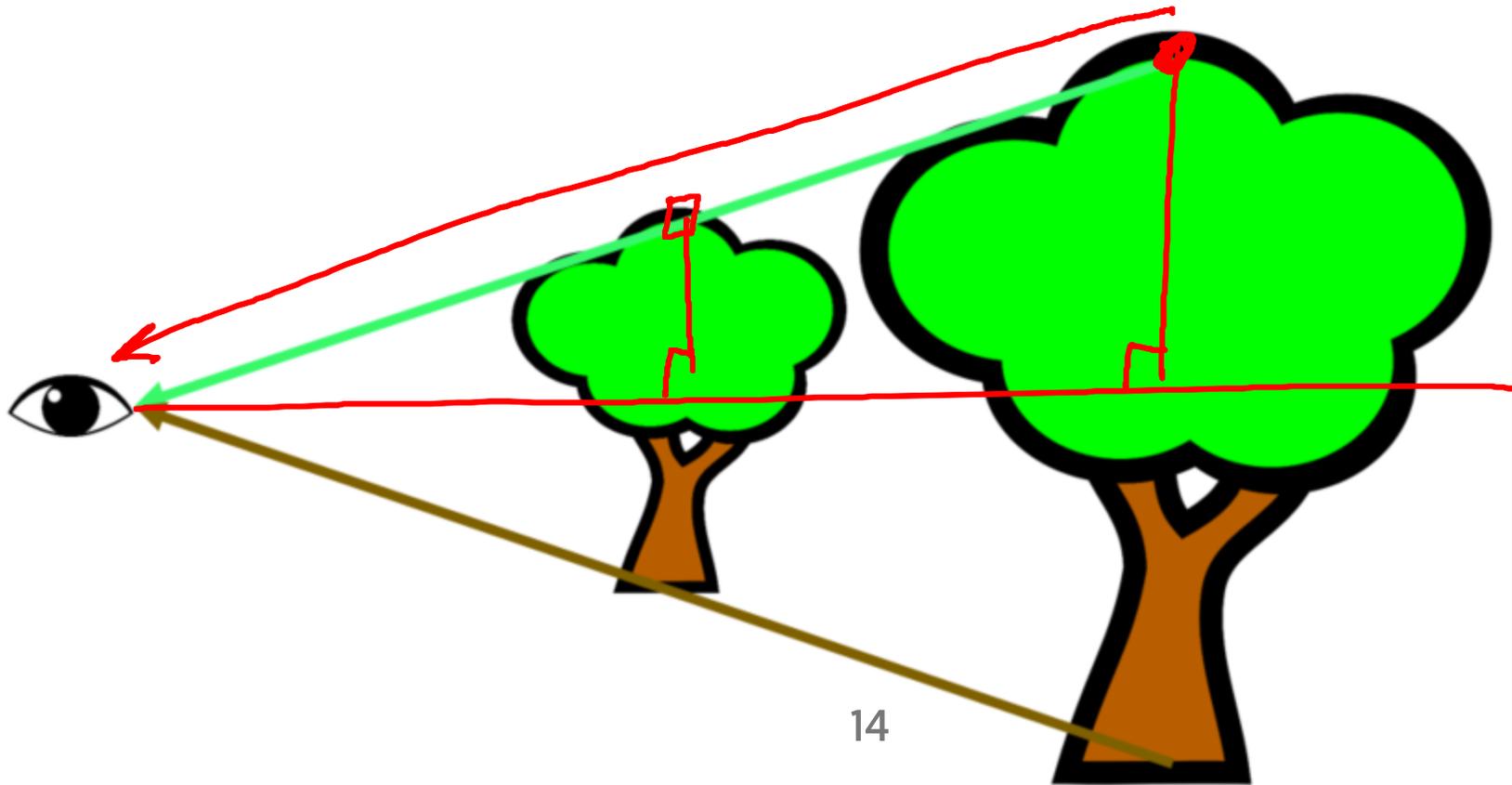
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# Perspective

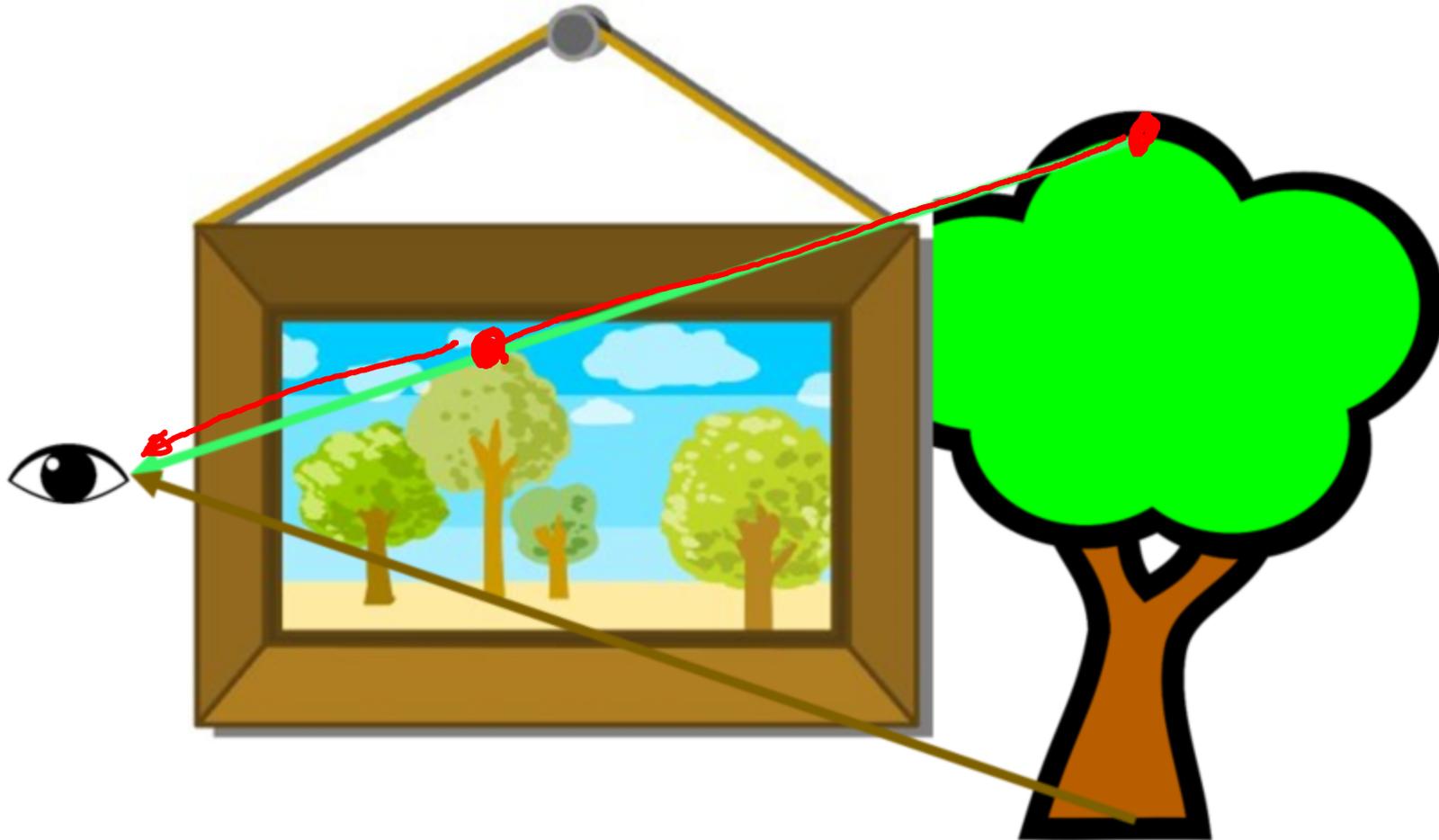
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Things that are far look smaller

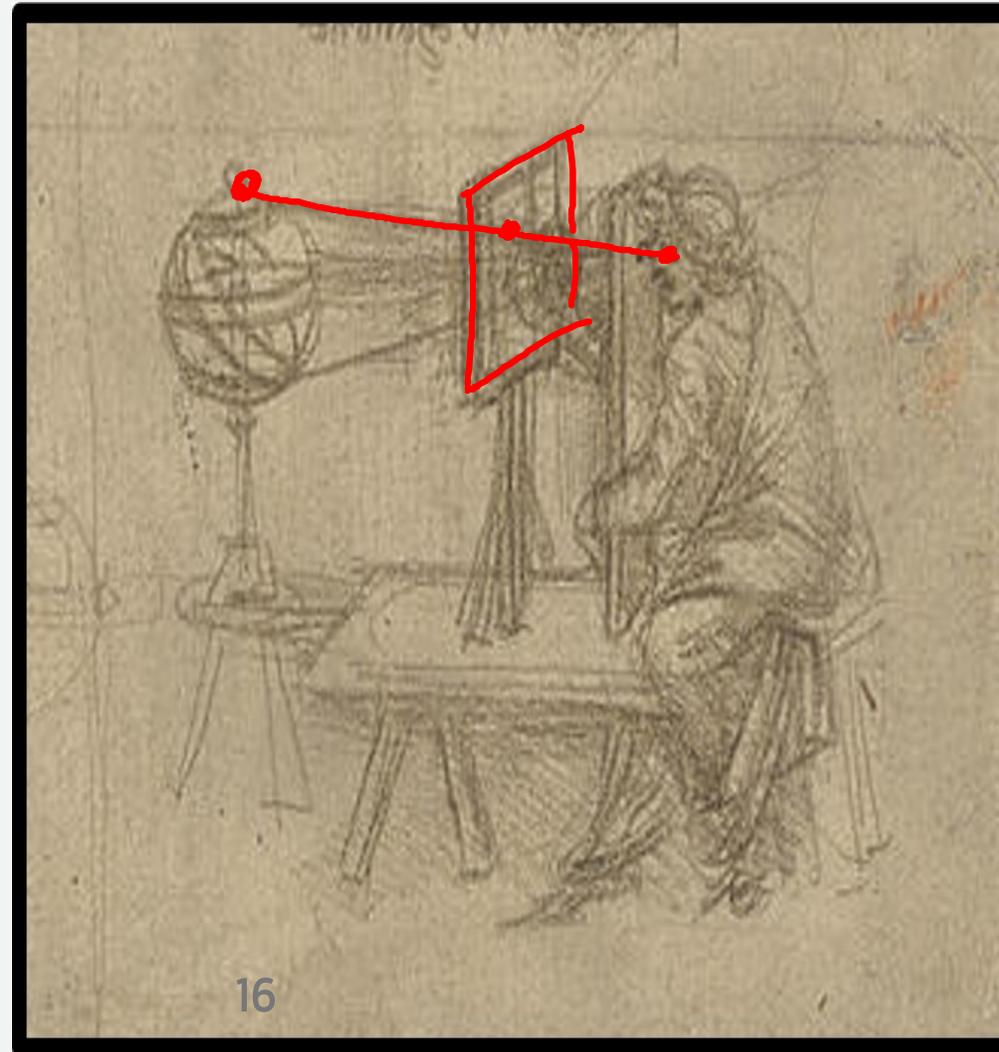
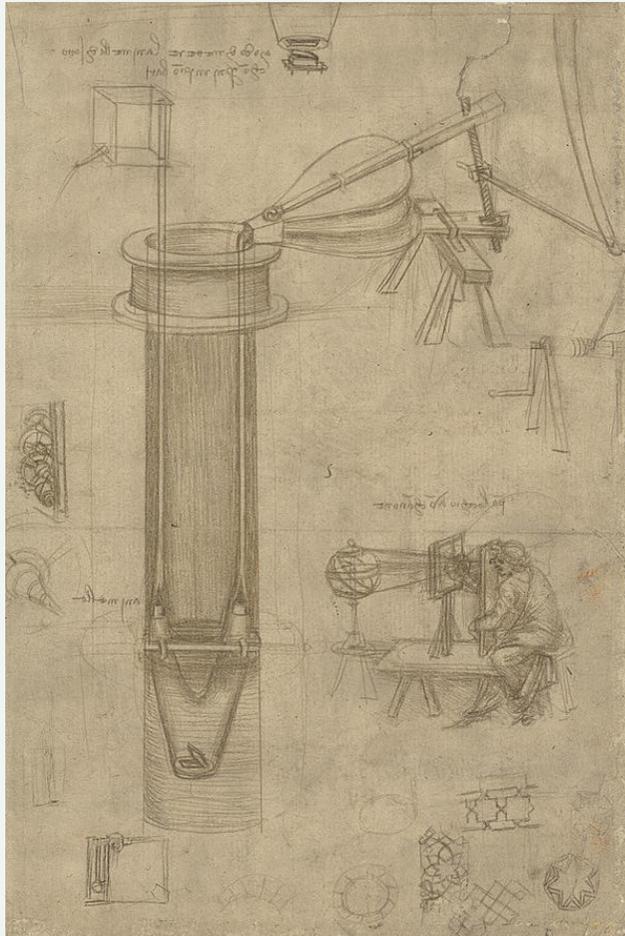


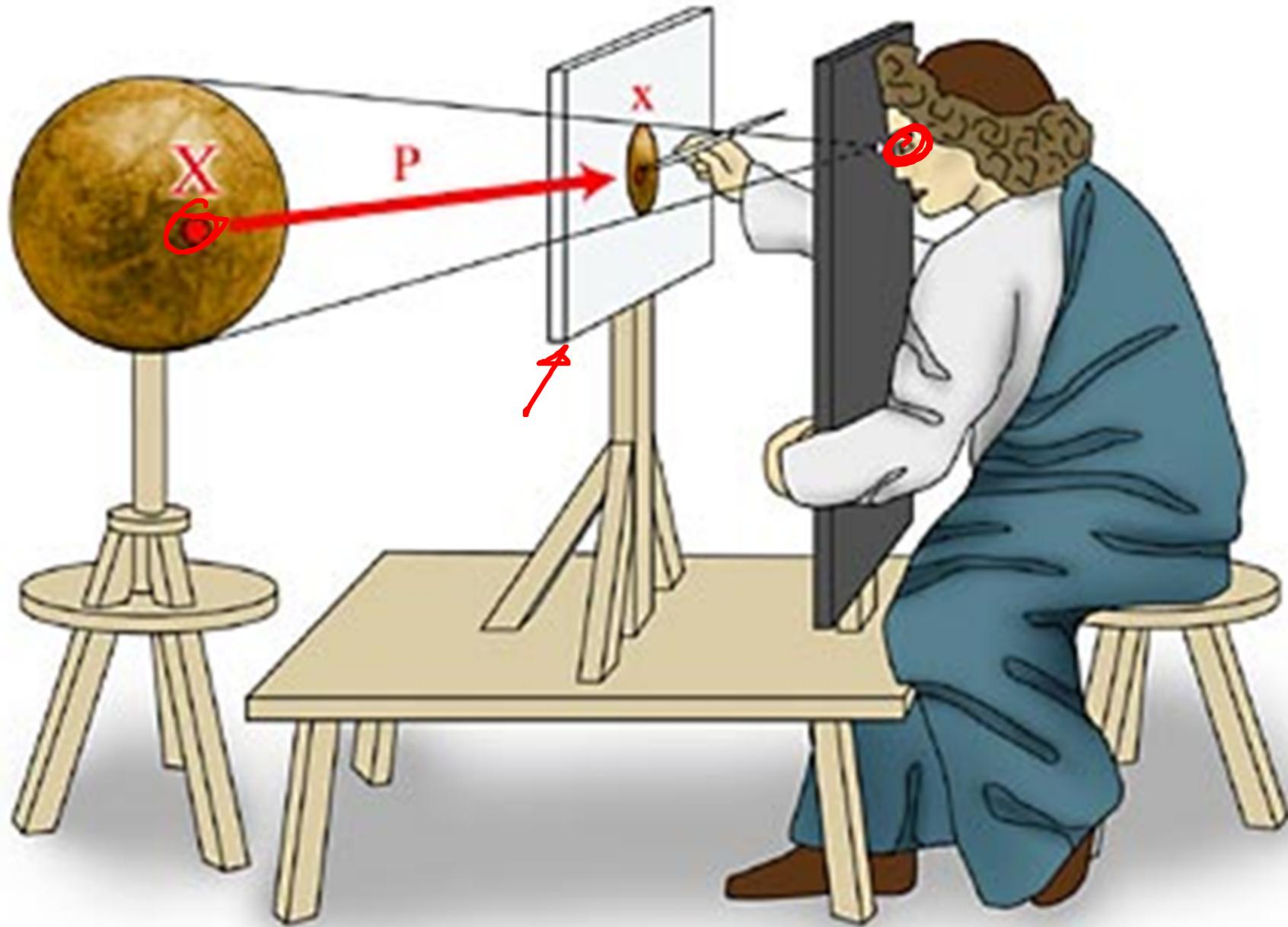
# Looking at things: Depth and Distance

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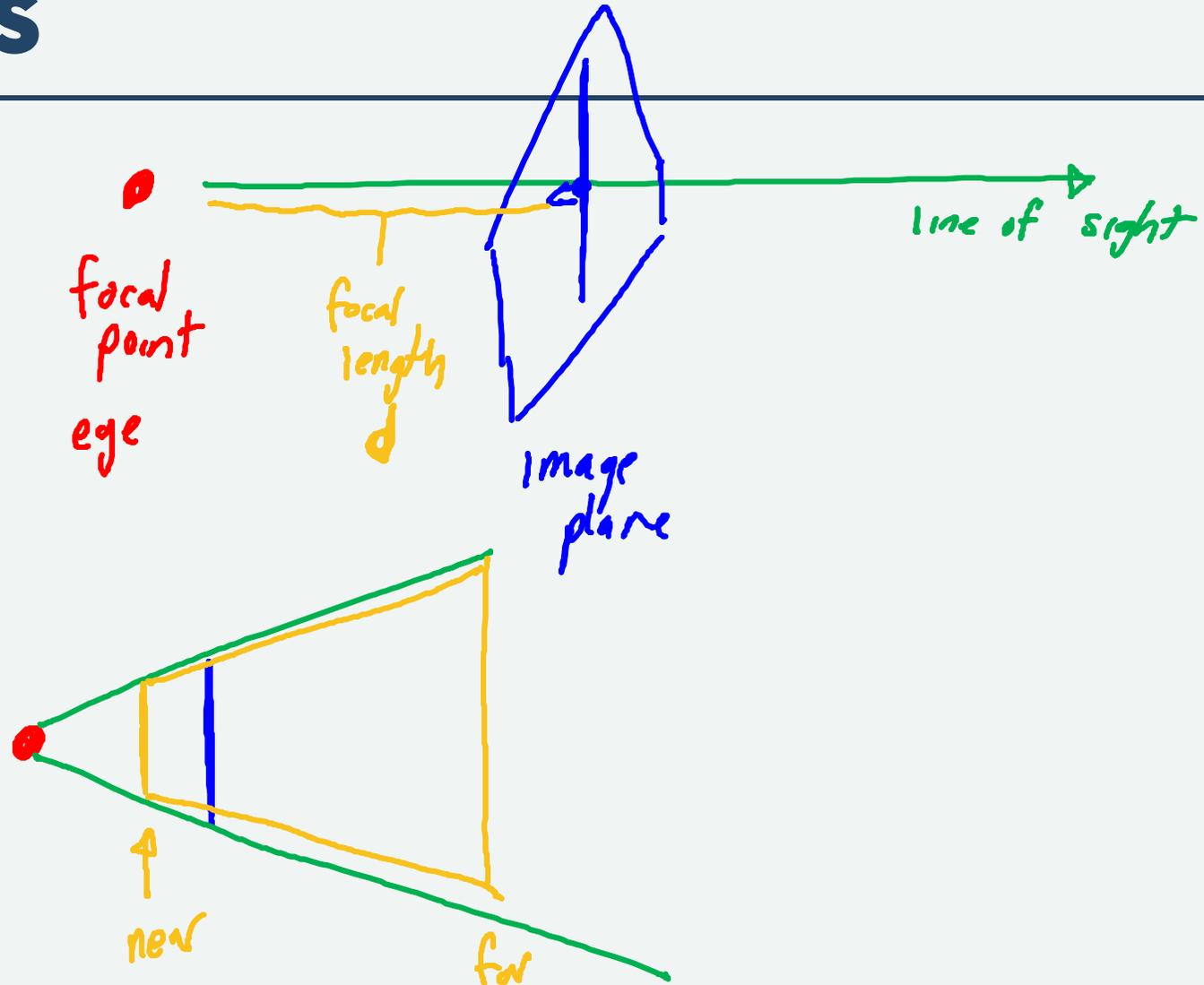
# Do it like Da Vinci!





# The intuitions

- focal point
- line of sight
- image plane
- focal length
- field of view
- frustum



# Some Assumptions

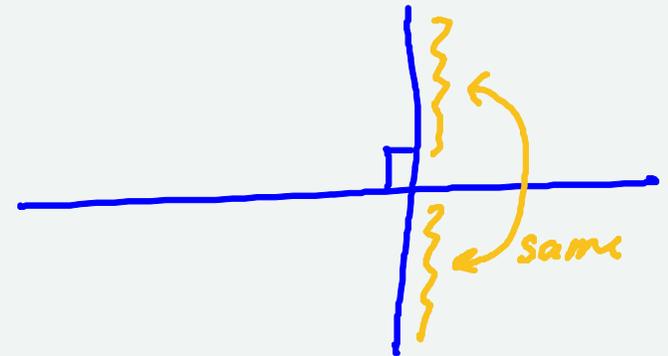
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Simple cameras: (general cameras can relax these)

- single focal point
- line of sight perpendicular to image plane
- line of sight centered

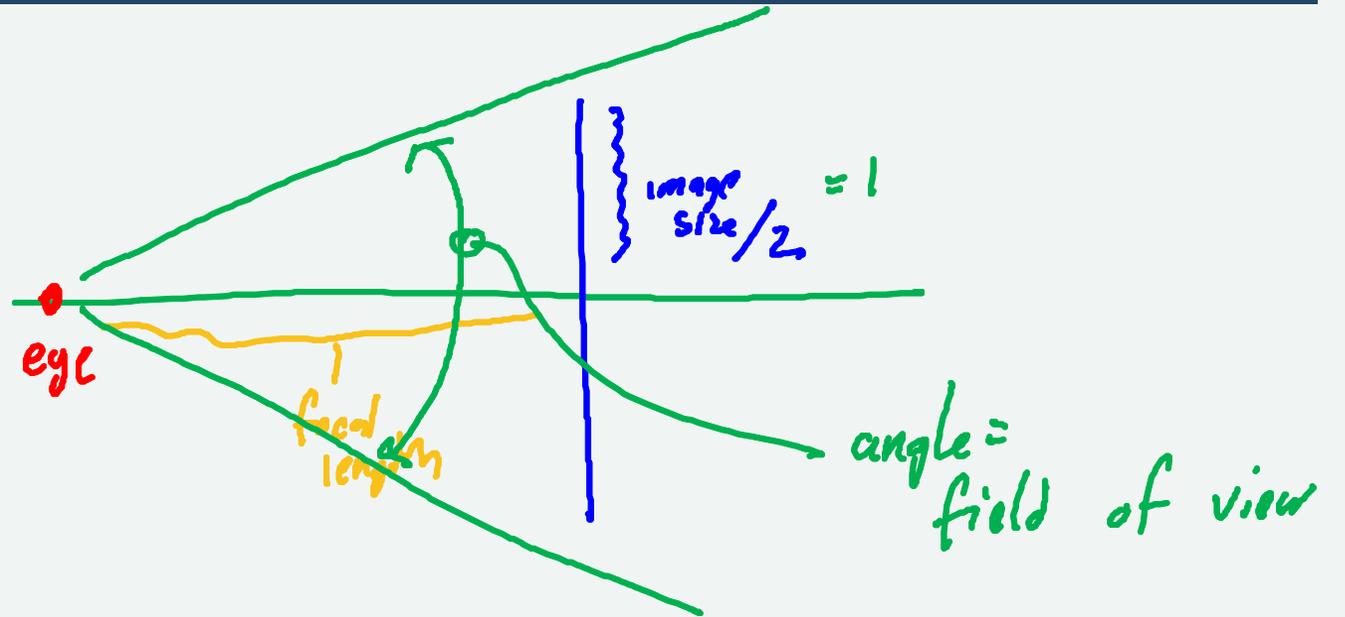
Simpler math

- sight down Z axis (or negative Z)



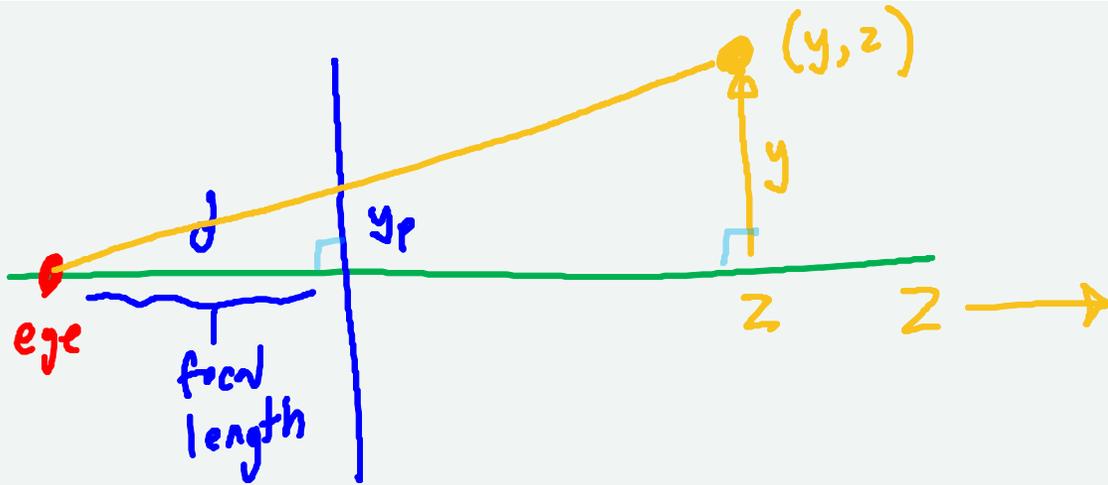
# Field of View vs. Focal Length

- angle
- distance (film size)



# Perspective Math: Similar Triangles

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$$\frac{y}{z} = \frac{y_p}{d}$$

$$y_p = \frac{y d}{z}$$

# The Math

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$$\underline{x}_s = \frac{d}{z} x$$

$$y_s = \frac{d}{z} y$$

$$z_s = d$$

This assumes that we are looking down the z axis

# Linear?

$$\begin{bmatrix} d & 0 & 0 & 0 \\ 0 & d & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

Diagram illustrating a linear transformation matrix and its input vector. The matrix is a 4x4 matrix with elements  $d, 0, 0, 0$  in the first row,  $0, d, 0, 0$  in the second row,  $0, 0, 0, 1$  in the third row, and  $0, 0, 1, 0$  in the fourth row. The input vector is  $\begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$ . A yellow arrow points to the  $x$  element in the vector. A blue circle highlights the first row of the matrix. A red circle highlights the third row of the matrix. A yellow circle highlights the  $1$  element in the fourth row of the matrix, with a yellow arrow pointing to the  $z$  element in the vector.

or

$$\underline{x_p = d x}$$

$$y_p = d y$$

$$\underline{z_p = 1}$$

$$\underline{w_p = z}$$

Don't forget the divide by w!

Note what happens to z

$$X_s = \frac{X_p}{W_p} = \frac{d x}{z}$$

$$Z_s = \frac{Z_p}{W_p} = \frac{1}{z}$$

# Z ordering

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Cannot keep  $z$ !

- if we divide by  $z$ , then the numerator would have to be  $z^2$

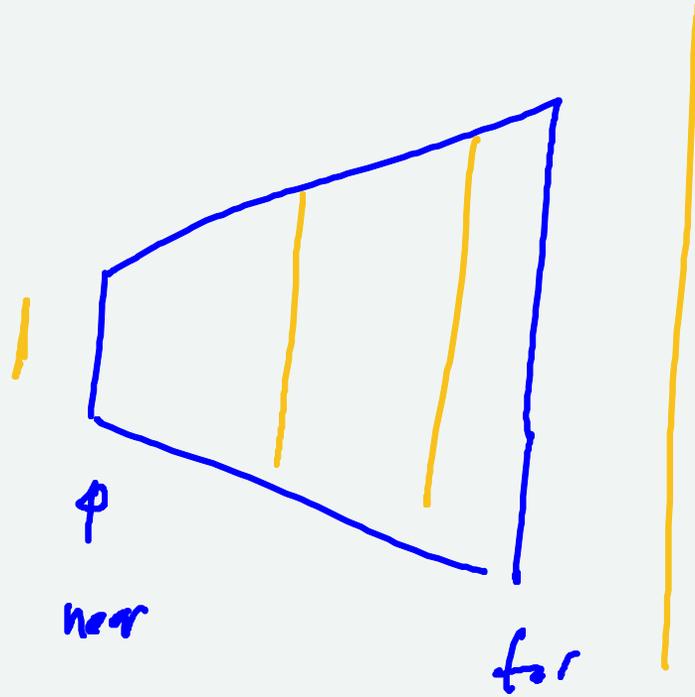
We can get  $\frac{1}{z}$

- preserves order (reverse - large  $Z$  is small value)
- breaks if  $z = 0$ , or negative
- shift  $z$  so it goes from near to far

# Near and Far

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Near is not the focal length



# Is it really that simple?

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Almost

A couple of catches:

- we need to scale  $z$  appropriately
- we need to scale  $x/y$  appropriately
- we're sighting down the positive/negative  $z$
- the book discusses this well

# The Matrix in the Book

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$$\begin{bmatrix} n & 0 & 0 & 0 \\ 0 & n & 0 & 0 \\ 0 & 0 & n + f & -fn \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$n$  - near plane distance

$f$  - far plane distance

# It's just a transformation!

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Just like any other linear transformation

# In THREE

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```
let cam = new T.PerspectiveCamera(fov, aspect, near, far);
```

- fov is angle in degrees
- aspect is width/height (needs to match canvas)
- near - anything closer is not seen
- far - anything farther is not seen

This is an Object3D.

It isn't visible, but it has all the transformations.

# Summary

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1. Projections and Fishtank Model
2. Near and Far
3. Orthographic Box
4. Perspective Concepts
5. Simple Perspective Model
6. Perspective Math (simple and in practice)
7. Persepctive in THREE